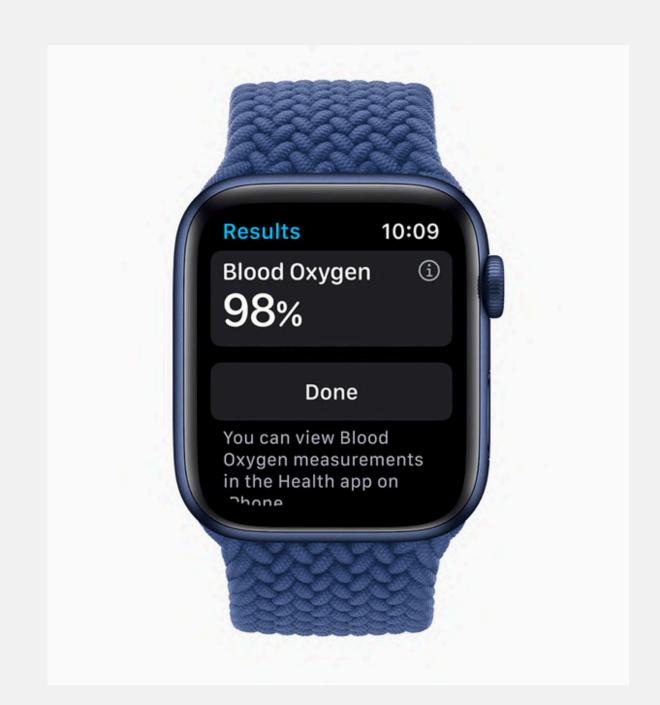
Parkinsons Detection On-the-fly using Wearables

BY: TRUSHA MAHESHWARI, RHEA SINGH, DEVAM AGARWAL

GROUP 33





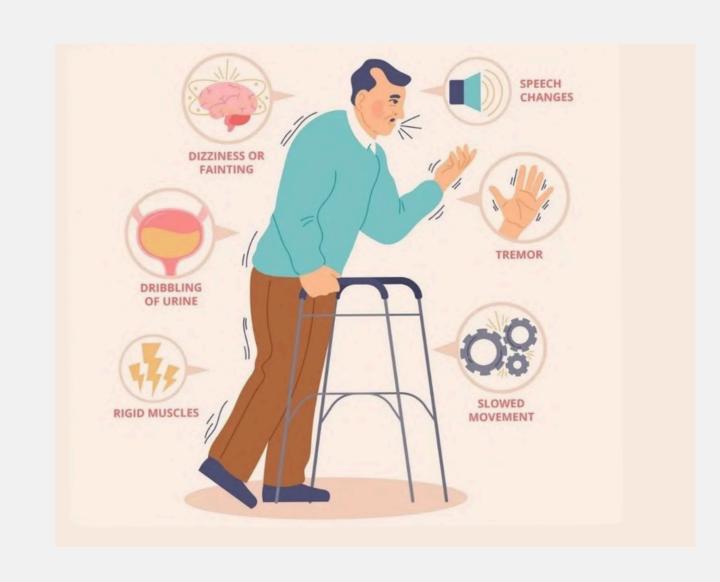




With smartwatches already so seamlessly integrated in our lives, can we use this piece of technology to detect a life-altering disease early on?

Parkinsons Disease

- A progressive neurodegenerative disorder primarily affecting movement.
- The hallmark symptoms: **bradykinesia** (slowness of movement), resting tremor, muscle rigidity, with postural instability often developing in later stages.
- Cause: remains unknown, but both genetic and environmental factors play roles.



Current Diagnosis Methods

- Clinical Examination & Medical History Neurologists assess symptoms like tremors, rigidity,
 and bradykinesia using criteria like MDS Clinical Diagnostic Criteria.
- Imaging Techniques **DaTscan (SPECT), MRI, and PET** scans help differentiate PD from other movement disorders.
- Levodopa Challenge Test Improvement in symptoms after taking Levodopa suggests Parkinson's.
- Motor & Non-Motor Assessments Includes UPDRS scale, gait analysis, handwriting tests, and olfactory tests (loss of smell).

Limitations

- All methods right now are detecting via clinical advancements, and more medically induced methods
 - Limited Accessibility: Techniques like DaTscan, MRI, and PET are expensive, not widely available, and impractical for routine screening.
 - Late Diagnosis: Clinical symptoms often appear after significant brain degeneration, delaying early intervention.
 - Lack of Continuous Monitoring: Traditional methods miss daily symptom fluctuations and early subtle changes, especially in non-motor symptoms.

Literature Review

American Academy Of Neurology



Accuracy of Parkinson disease diagnosis unchanged in 2 decades

Ali H. Rajput and Alex Rajput

Neurology 2014;83;386-387 Published Online before print June 27, 2014

DOI 10.1212/WNL.0000000000653

- Diagnostic Accuracy: An accuracy rate of 77% indicates that approximately one in four PD diagnoses may be incorrect.
- The study highlights that neurologists often rely heavily on clinical skills due to limited diagnostic tools in movement disorders. This reliance can contribute to diagnostic inaccuracies.
- The lack of improvement in diagnostic accuracy over two decades suggests that advancements in diagnostic methodologies or technologies have been minimal, pointing to a need for better diagnostic approaches.

Challenges in the diagnosis of Parkinson's disease

Eduardo Tolosa*, Alicia Garrido, Sonja W Scholz, Werner Poewe*

Hospital Clinic of Barcelona, University of Barcelona

- Despite numerous advancements, early-stage Parkinson's remains difficult to diagnose due to symptom overlap with other neurodegenerative disorders.
- While imaging (e.g., PET, DaTscan) and biomarkers are promising, they lack universal accessibility and standardization, making them impractical for widespread use.

Lancet Neurol 2021; 20: 385-97

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Red Sobre Enfermedades
Neurodegenerativas
(CIBERNED), Hospital Clínic,
IDIBAPS, Universitat de
Barcelona, Barcelona, Spain
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Article Open access Published: 05 January 2024

Machine Learning in the Parkinson's disease smartwatch (PADS) dataset

Julian Varghese ☑, Alexander Brenner, Michael Fujarski, Catharina Marie van Alen, Lucas Plagwitz & Tobias Warnecke

Computational Expensive:

High due to multi-source data processing, feature extraction, deep learning complexity, and cross-validation for distinguishing similar disorders.

• Accuracy:

The model achieved 91.16% accuracy for PD vs. healthy controls and 72.42% for PD vs. differential diagnoses, highlighting challenges in distinguishing similar disorders.

Deployment:

The current model is unsuitable for deployment on smartwatches due to its high computational cost.

Drawbacks of the current methodology

1. Feature Selection Methodology

- Features are selected manually
- Then this **limited set** is fed into deep learning models.
- Causes the **loss of potentially important information** due to hand-picked features as model extracts from less data.

2. High Computation Cost

- Tests multiple models on different feature sets and reports the best performing model.
- Unnecessarily heavy as all models need to be simultaneously run.

Problem Statement

Can we develop a machine learning model for the early prediction of Parkinson's disease using movement sensor data and self-reported questionnaire responses?

Datasets

Movement/Motor Dataset:

- Accelerometer
- Gyroscope

Questionnaire Dataset:

Subjective Self-Reported Symptom responses

Patient Dataaset:

Condition, Age, Gender, etc.

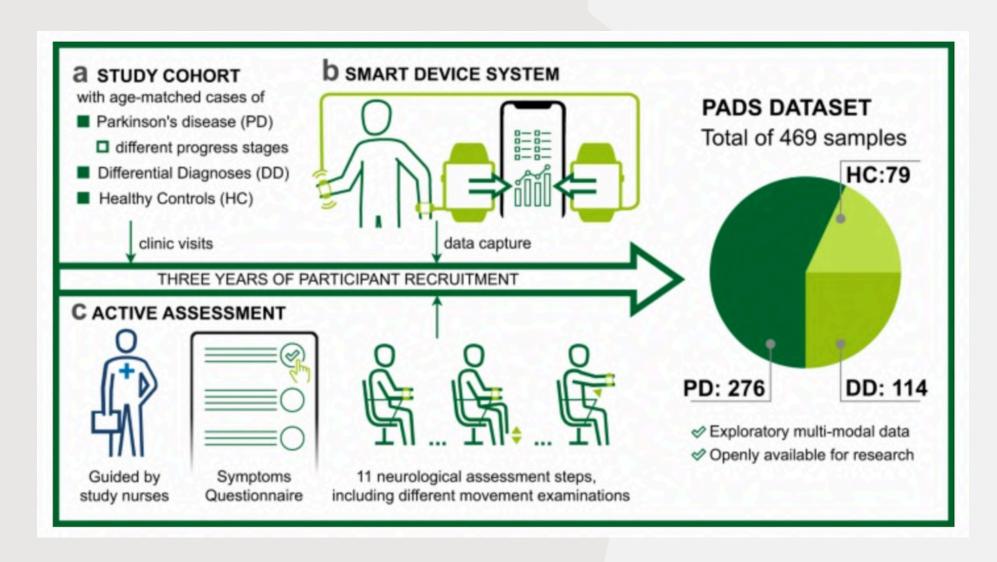
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          "Gyroscope Z"
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          "g",
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```

Data Collection

This data is sourced via:

- 3-year cross-sectional study at a large tertiary care hospital
- A multi-modal smartphone app integrated
 electronic questionnaires and smartwatch
 measures during an interactive assessment designed
 by neurologists to provoke subtle changes in
 movement pathologies.
- 5000 clinical assessment steps from 504 participants,
 including PD, DD, and healthy controls (HC).



Preprocessing

Multimodal Data

pads-parkinsons-disease-smartwatch-dataset-1.0.0								
Name	Date Modified Size	Kind						
scripts	Today at 4:15 AM	- Folder						
preprocessed	08-Mar-2025 at 10:38 PM	- Folder						
questionnaire	07-Mar-2025 at 4:15 PM	- Folder						
patients	07-Mar-2025 at 4:15 PM	- Folder						
movement movement	07-Mar-2025 at 4:15 PM	- Folder						
SHA256SUMS.txt	26-Mar-2024 at 2:25 AM 1.4 MB	B Plain Text						
LICENSE.txt	19-Mar-2024 at 11:47 PM Zero bytes	Plain Text						

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001_CrossArms_LeftWrist.txt	12-Ma
001_CrossArms_RightWrist.txt	12-Ma
001_DrinkGlas_LeftWrist.txt	12-Ma
001_DrinkGlas_RightWrist.txt	12-Ma
001_Entrainment_LeftWrist.txt	12-Ma
001_Entrainment_RightWrist.txt	12-Ma
001_HoldWeight_LeftWrist.txt	12-Ma
001_HoldWeight_RightWrist.txt	12-Ma
001_LiftHold_LeftWrist.txt	12-Ma
001_LiftHold_RightWrist.txt	12-Ma
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patients			
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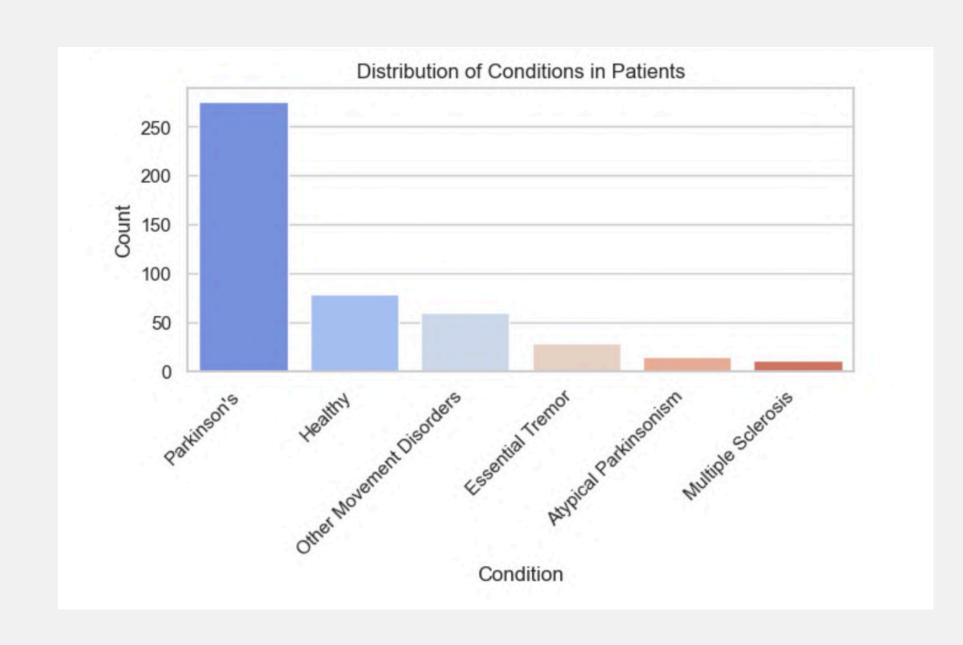
Integrating Multiple Datasets

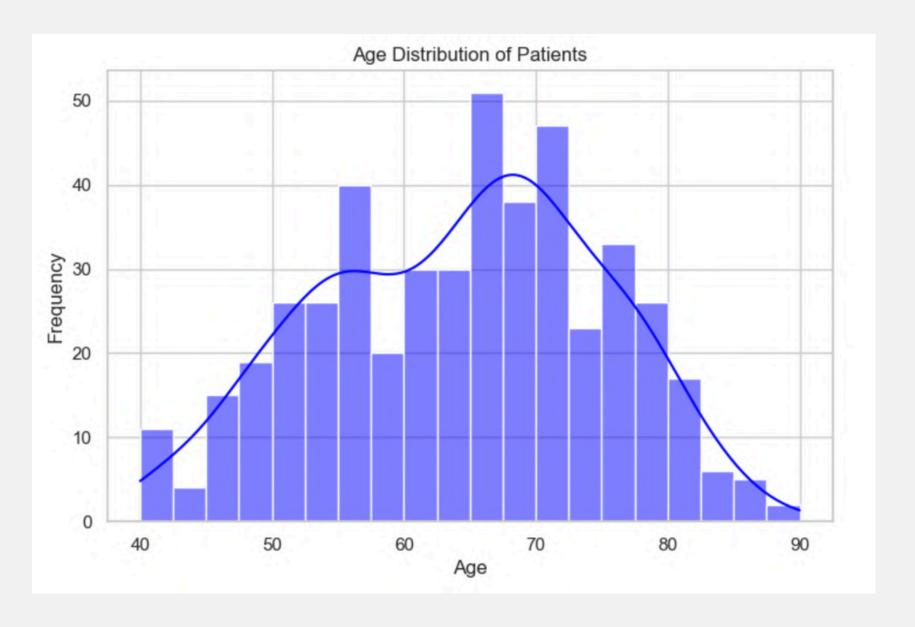
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patient	36 PADS	Multiple Scle	Multiple Scle	24	40	183	75	male	right	TRUE	TRUE	No effect
patient	54 PADS	Healthy		40	40	183	88	female	right	TRUE	TRUE	No effect
patient	193 PADS	Healthy	- 1	40	40	183	78	male	right	FALSE	FALSE	Unknown
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patient	77 PADS	Other Moven	Dystonial tre	37	41	170	60	female	right	FALSE		No effect
patient	178 PADS	Other Moven	SWEDD	0	41	174	66	female	left	TRUE	TRUE	No effect
patient	250 PADS	Healthy		42	42	168	68	female	right	FALSE	FALSE	Unknown
patient	276 PADS	Other Moven	ET DD function	14	42	178	62	female	right	TRUE	FALSE	Unknown
patient	307 PADS	Parkinson's	IPS with dysto	37	42	193	90	male	right	FALSE		Unknown
patient	367 PADS	Other Moven	IPS tremordo	38	42	174	72	female	left	TRUE	TRUE	No effect
patient	444 PADS	Healthy	÷	42	42	170	62	female	right	FALSE	1201	No effect
patient	176 PADS	Other Moven	Bacterial Me	0	43	168	110	female	right	FALSE	FALSE	No effect
patient	438 PADS	Multiple Scle	MS type Bali,	30	43	173	85	male	right	FALSE	FALSE	Improvement
patient	287 PADS	Other Moven	Adult multifo	43	44	167	68	female	left	FALSE		Unknown
patient	408 PADS	Healthy		44	44	167	50	female	right	FALSE	FALSE	Unknown
patient	3 PADS	Healthy	ş 4	45	45	170	78	female	right	FALSE	1. 7. 10 2. 0	Unknown
patient	50 PADS	Other Moven		37	45	174	56	female	right	FALSE		Unknown
patient	445 PADS	Essential Tre	-	45	45	165	53	female	right	FALSE		Improvement
patient	449 PADS	Healthy	-	45	45	194	109	male	right	TRUE	TRUE	No effect
patient	71 PADS	Parkinson's	IPS tremordo	33	46	184	110	male	right	FALSE		Unknown
patient	86 PADS	Parkinson's	IPS hypokinet	40	46	163	69	female	right	TRUE	FALSE	Unknown
patient	111 PADS	Other Moven	Tremor of unk	42	46	163	76	female	right	FALSE		Worsening
patient	162 PADS	Parkinson's	IPS akinetic-ı	35	46	168	69	female	right	FALSE		Unknown
patient	268 PADS	Parkinson's	Segmental dy	43	46	183	97	female	right	FALSE	4.2	No effect
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patient	65 PADS	Parkinson's	IPS mixed typ	32	47	175	70	male	right	FALSE	F1	No effect
patient	305 PADS	Parkinson's	StartingIPSt	47	47	196	110	male	right	FALSE		No effect
patient	380 PADS	Parkinson's	IPS hypokinet	47	47	179	76	male	right	FALSE		Unknown
patient	412 PADS	Parkinson's	IPS hypokinet	43	47	158	54	female	right	FALSE	14 48	Worsening
patient	451 PADS	Other Moven	Unknown Tre	42	47	162	76	female	right	FALSE		Improvement
patient	29 PADS	Parkinson's	IPS, THS	33	48	175	70	male	right	FALSE		No effect
patient	121 PADS	Healthy		48	48	172	73	female	right	TRUE	TRUE	Unknown
patient	134 PADS	Healthy	4,7.4.7.1	48	48	184	90	male	right	FALSE	FALSE	Unknown
nationt	201 DADS	Darkineon'e	IDS mivad tun	16	ΛQ	150	57	famala	right	EVICE		No offect

DATASETS

- clean-questionnaire-data
 - clean_questionnaire_data.csv
- ▼ formatted-questionnaire-data
 - Questionnaire_Data_with_ID.csv
 - pd_dd_formatted.csv
 - pd_hc_formatted.csv
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Data Spread





Smartwatch Data (Time Series Data)

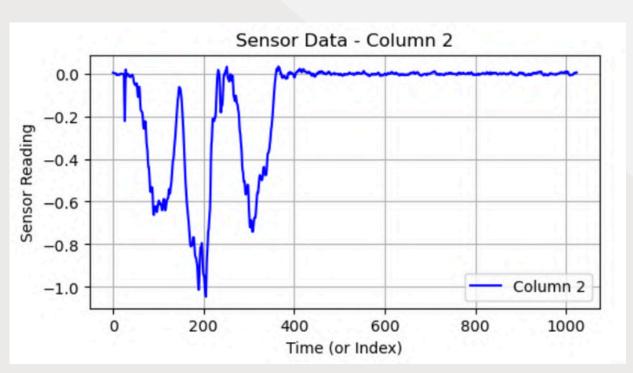
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008 LiftHold RightWrist.txt

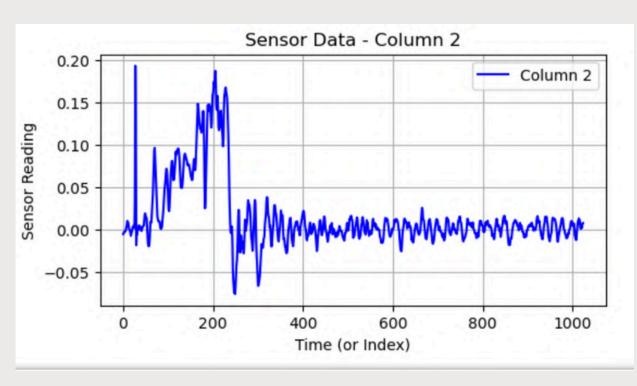
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Accelerometer

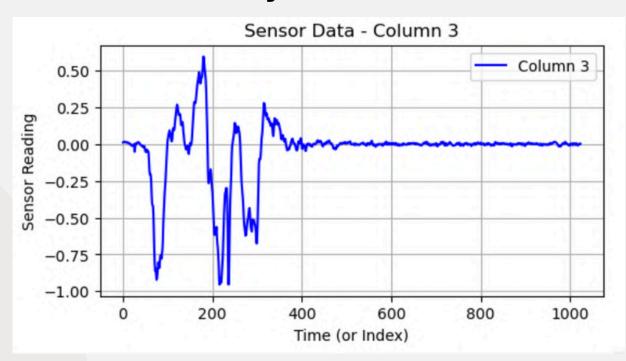
x-axis



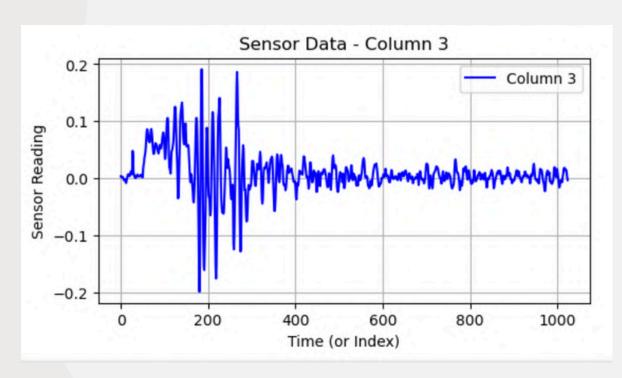
HC



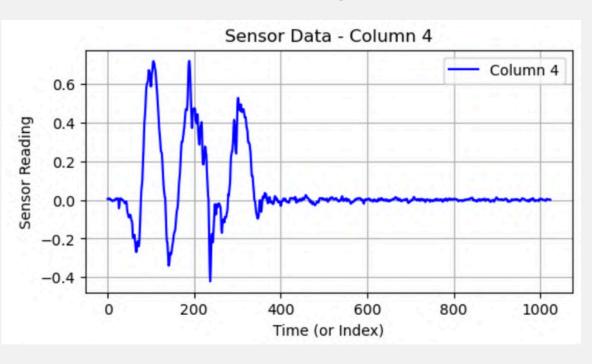
y-axis



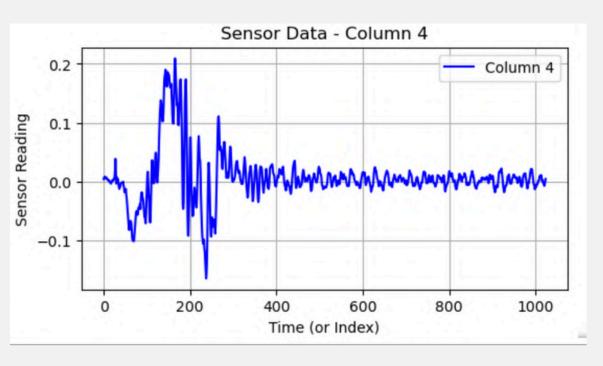
HC



z-axis

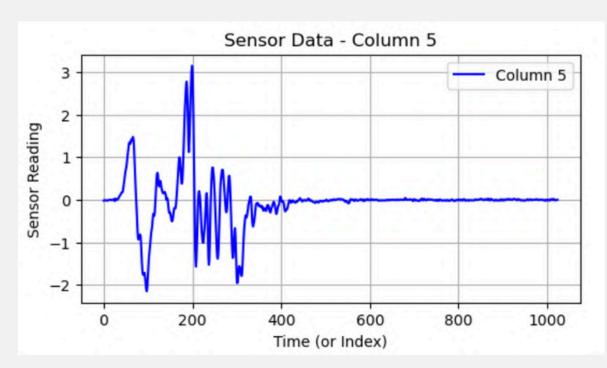


HC

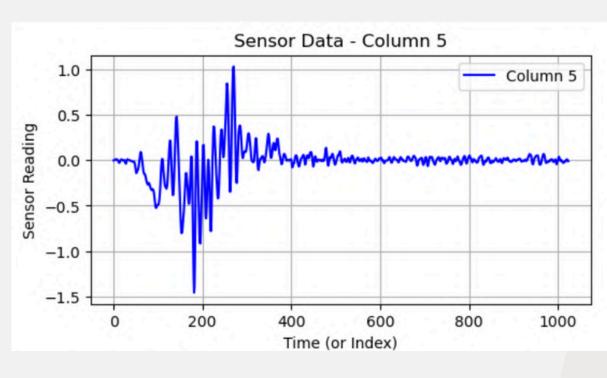


Gyroscope

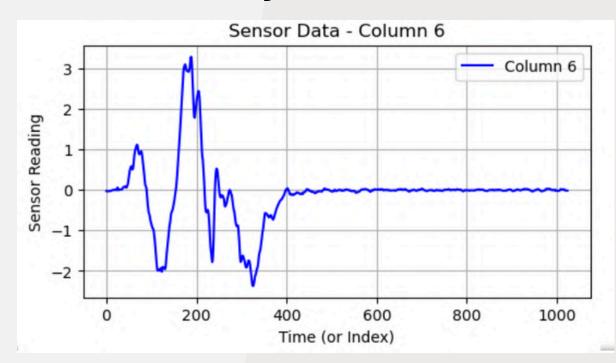
x-axis



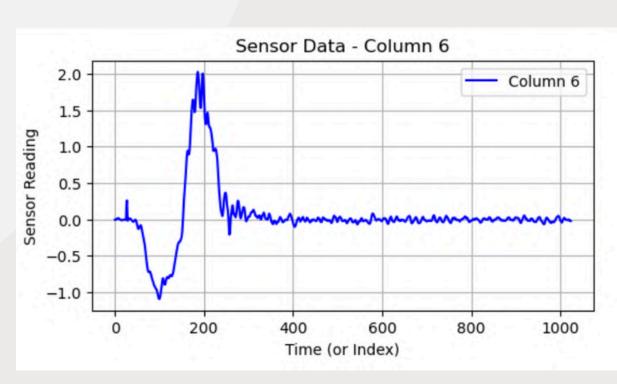
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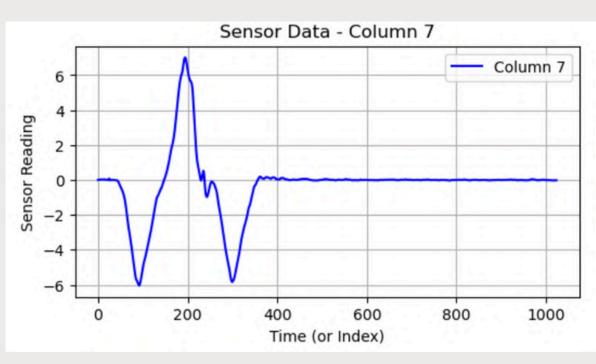
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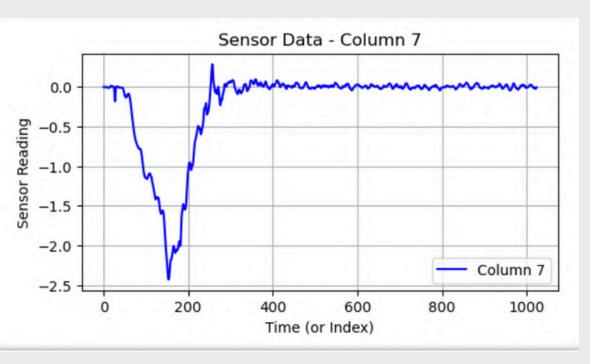
HC



z-axis

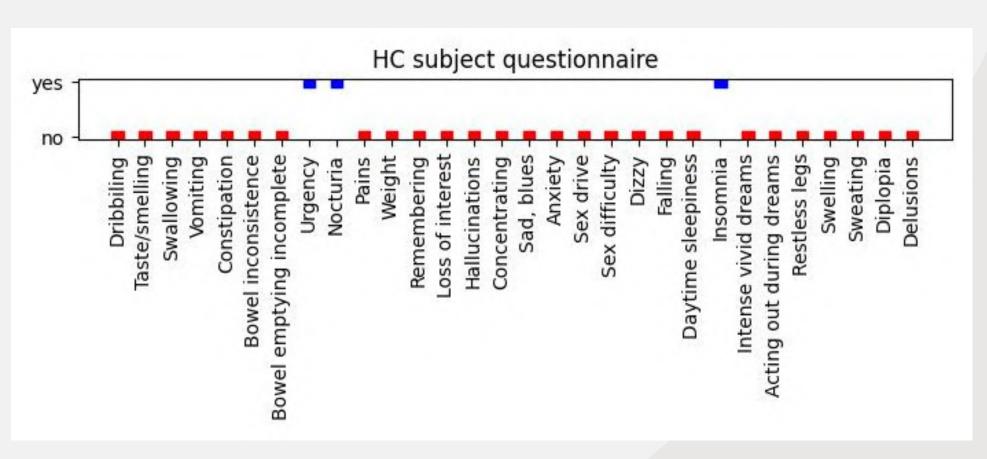


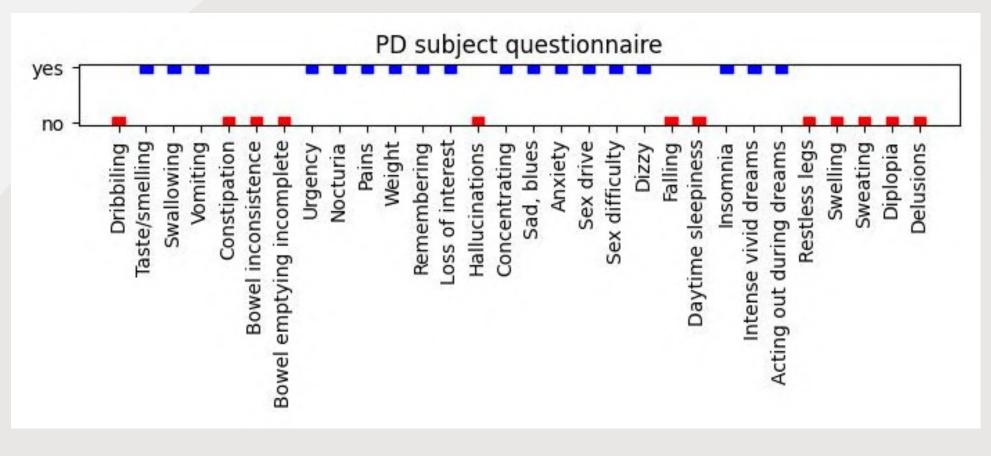
HC



PD

Questionnaire





ML Methodology

Motor Model - What Didn't Work

Attempted: Omni-Scale CNN

Reason:

- Inspired by **XceptionTime**; expected good performance on multimodal signals.
- Why Omni-Scale: **Computationally light**, good for small devices (smartwatches).

What we tried:

• **Hyperparameter tuning** (grid search on learning rate, neurons, depthwise separable conv).

Outcome:

- Accuracy plateaued early (~mid 60s%).
- Adding layers didn't help which meant convolutions not learning useful features.

Learning:

 Non-Convolutional models may work better for time-series motor features. Cross-validation results:

Average accuracy: 0.6610

Average precision: 0.6617

Average recall: 0.8655

Average f1: 0.7484

Average auc: 0.7010

Questionnaire Model - What Worked

Baseline: Feedforward Neural Network

Achieved:

- Training accuracy: 84%
- Test accuracy: 80%
- No signs of overfitting.

Simple model worked well → stuck with it for

		precision	recall	f1-score	support	
	0.0	0.75	0.69	0.72	35	
	1.0	0.82	0.86	0.84	59	
accui	racy			0.80	94	
macro	avg	0.79	0.78	0.78	94	
weighted	avg	0.80	0.80	0.80	94	
Training	Set	Evaluation:				
		precision	recall	f1-score	support	
	0.0	0.81	0.81	0.81	158	
	1.0	0.86	0.86	0.86	217	
accui	racy			0.84	375	
macro	avg	0.83	0.83	0.83	375	
weighted	avg	0.84	0.84	0.84	375	

fusion.

Moving to a Fusion Model

Fusion

Concatenated raw features → fed to basic random forest.

Result:

Accuracy: late 60s

Improvement:

Feature Engineering

Extracted features from motor data:

Statistical: Mean, std, min, max, RMS, skewness, kurtosis, FFT energy

Wavelet: Mean, std, energy across levels (PyWavelets)

Cross-channel: Correlation and phase differences

Combined with questionnaire responses.

Feature Extraction Approach

Architecture

- ParkinsonClassifier (MLP): Motor features
- QuestionnaireNN (MLP): Questionnaire
- FusionModel: Concatenates both

Performance:

- PD vs HC: 81.69%
- PD vs DD: **74.36**%
- Close to the results in the literature review using only simple, interpretable models

Test Set Metrics: Accuracy: 0.8169 Precision: 0.8088

Recall: 1.0000

F1: 0.8943 Auc: 0.9852

PD vs HC

Test Set Metrics: Accuracy: 0.7436 Precision: 0.7397

Recall: 0.9818

F1: 0.8438 Auc: 0.8664

PD vs DD

Final Fusion Model Architecture

Model Architecture:

- Input: Extracted motor features
- 3 hidden layers → BatchNorm + ReLU + Dropout
- Questionnaire MLP):
- Input: Scaled questionnaire features
- 2 hidden layers → ReLU + Dropout

FusionModel:

- Concatenates both branches
- Final FC layers → Sigmoid output

Training Setup:

- Early stopping
- 5-fold stratified cross-validation
- Train/test split = 80/20

Results:

- Accuracy (PD vs DD): ~98.72%
- Accuracy (PD vs HC): ~100%
- Robust generalization across validation & test splits

```
Best validation metrics: {'acc': 1.0, 'prec': 1.0, 'rec': 1.0, 'f1': 1.0, 'auc': 1.0}

Evaluating best model on test set...

Test Set Metrics:
Accuracy: 0.9872
Precision: 0.9821
Recall: 1.0000
F1: 0.9910
Auc: 1.0000
```

PD vs DD

```
Best model was from fold 1 with validation loss 0.0013
Best validation metrics: {'acc': 1.0, 'prec': 1.0, 'rec': 1.0, 'f1': 1.0, 'auc': 1.0}

Evaluating best model on test set...

Test Set Metrics:
Accuracy: 1.0000
Precision: 1.0000
Recall: 1.0000
F1: 1.0000
Auc: 1.0000
```

PD vs HC

Best validation metrics: {'acc': 1.0, 'prec': 1.0, 'rec': 1.0, 'f1': 1.0, 'auc': 1.0}

Evaluating best model on test set...

Test Set Metrics: Accuracy: 0.9872 Precision: 0.9821 Recall: 1.0000 F1: 0.9910 Auc: 1.0000

Best validation metrics: {'acc': 1.0, 'prec': 1.0, 'rec': 1.0, 'f1': 1.0, 'auc': 1.0}

Evaluating best model on test set...

Test Set Metrics: Accuracy: 1.0000 Precision: 1.0000 Recall: 1.0000 F1: 1.0000

Auc: 1.0000

PD vs DD

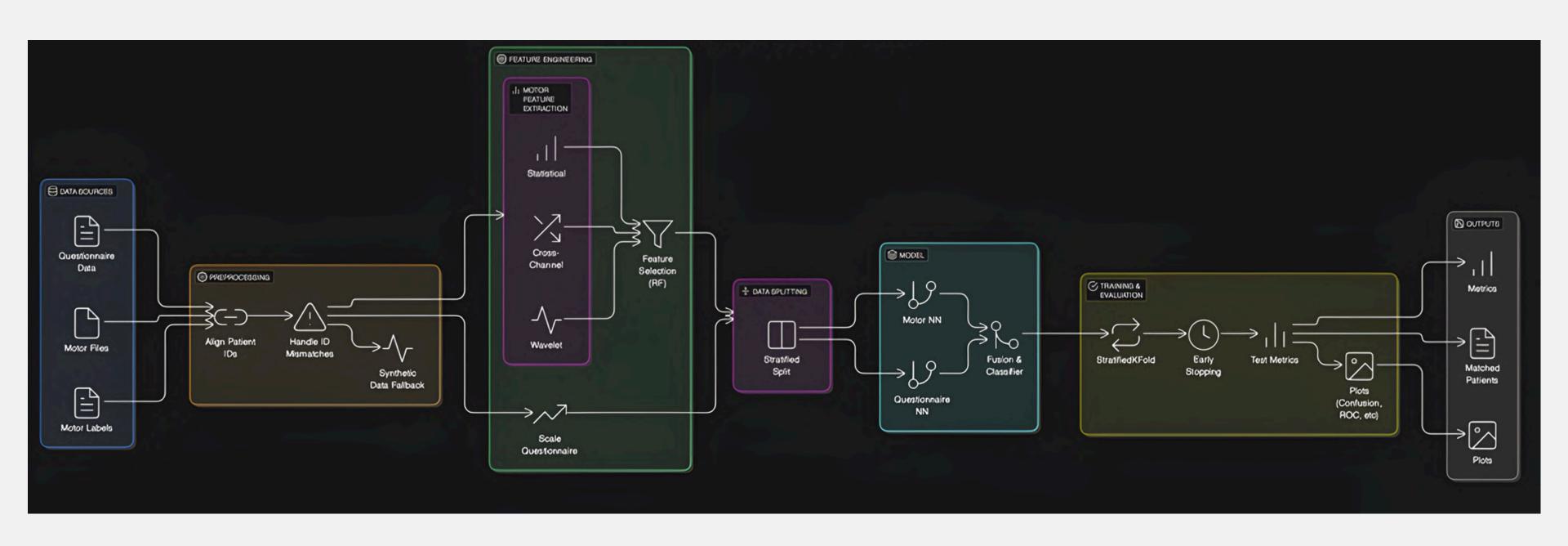
PD vs HC

Input	Test folds	Balanced accuracy	F1	Precision	Recall
Smartwatch + Questionnaire	complete	72.42% (12.33%)	60.45% (16.7%)	54.92% (15.05%)	67.71% (19.45%)
	matched	69.56% (17.34%)	67.93% (19.84%)	70.36% (19.85%)	65.71% (19.93%)

PD vs DD

Smartwatch + Questionnaire	complete	91.16% (4.92%)	94.62% (2.21%)	96.98% (2.49%)	92.4% (2.64%)
	matched	89.25% (5.65%)	89.77% (5.24%)	89.79% (8.99%)	90.11% (3.13%)

Pipeline



PD vs. All Classification

Auc: 0.8275

Motor Branch (ParkinsonClassifier)

- Fully connected layers (256 → 128 → 64)
- Inputs: Extracted features from motor data
- Statistical
- Wavelet
- Cross-channel correlation
- Feature selection via Random Forest

Questionnaire Branch (QuestionnaireNN)

- Two-layer feedforward network (128 → 64)
- Inputs: Cleaned & scaled questionnaire data

Fusion Head (FusionModel)

- Concatenation of both branches
- Final classifier: 64 → 1 with Sigmoid activation

Outcomes

Added depth seperable convolution layers-

- Accuracy dropped by ~10%
- Validated our hypothesis that linearly separable models work better for our features.

Extracted features + Neural Networks worked best

Smaller model (around 2 MB size)

Better suited for edge deployment (e.g., on wearables)

Challenges with Scaling Up

1. Limited Labeled Data

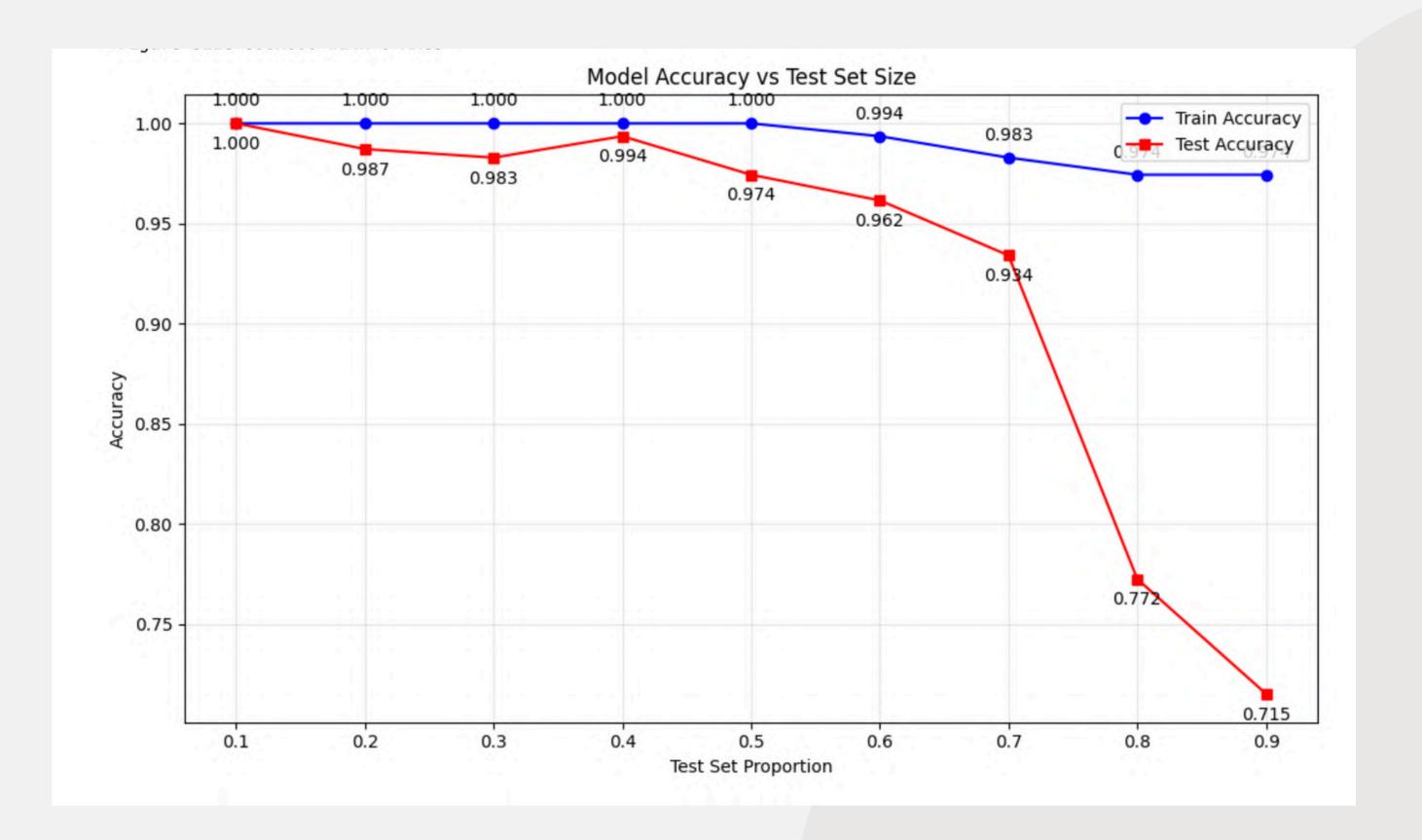
- Small number of patients with both motor and questionnaire data.
- Difficult to scale without significantly more labeled, multimodal samples.

2. Class Imbalance

- Parkinson's datasets are often imbalanced, especially with rare atypical subtypes.
- Scaling up requires robust class-weighting or synthetic sample generation (e.g., SMOTE).

3. Infrastructure & Compute

- Large-scale feature extraction + training demands high memory and GPU.
- Scaling may need batch processing pipelines, cloud GPU infrastructure.



Thank you